

# Zhening ZHU

fvvv0850@leeds.ac.uk | +44 07586 682743 | [Website](#)

## EDUCATION

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<b>University of Leeds</b> , Leeds, UK	<b>2025.09 - Present</b>
PhD Computer Science (EPSRC Doctoral Landscape Award Studentship)	
Topic: Perceptual graphics / bandwidth reduction using perceptual rendering	
<b>Cornell Tech (Cornell University)</b> , New York, USA	<b>2024.08 - 2025.05</b>
MEng Computer Science   GPA: 4.0	
<b>University of Nottingham</b> , Ningbo, CN; Nottingham, UK	<b>2020.09 - 2024.07</b>
BSc Hons Computer Science   GPA: 3.99	

## RESEARCH EXPERIENCE

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<b>Real-Time Perceptual Spatial Quantization for Foveated Rendering</b>	<b>2025.12 - 2026.04</b>
<i>EGRS2026 (Accepted)</i>   <a href="#">Visualization and Computer Graphics Lab</a> , University of Leeds	
<ul style="list-style-type: none"> <li>Conducted a comprehensive literature review on color perception and gaze-contingent rendering.</li> <li>Designed algorithm and workflow for gaze-contingent color bit-depth reduction for foveated streaming.</li> <li>Conducted perceptual experiments to examine discrimination for spatial quantization.</li> <li>Achieved 83% data bandwidth reduction compared to standard 24-bit true color frame.</li> </ul>	
<b>MRTodo: Synchronizing Paper and Digital To-Do Lists in Mixed Reality</b>	<b>2025.04 - 2025.09</b>
<a href="#">VVAI Lab</a> , Texas A&M	
<ul style="list-style-type: none"> <li>Designed and developed a context-aware productivity application.</li> <li>Designed and executed user study, including both qualitative interviews and quantitative surveys to evaluate usability, effectiveness, and user satisfaction.</li> </ul>	
<b>Real-time Localization &amp; 3D Scene Visualization</b>	<b>2024.07 - 2024.08</b>
<a href="#">Advanced Display and Sensing Research Center</a> , Yongjiang Laboratory	
<ul style="list-style-type: none"> <li>Developed a web-based interactive tool to visualize real-time SLAM localization of camera pose and 3D scene reconstruction results.</li> </ul>	
<b>Transmogripher Game: Visuomotor misalignment for Non-humanoid Avatars</b>	<b>2023.10 - 2024.05</b>
<i>Undergraduate Dissertation</i>   <a href="#">Mixed Reality Lab</a> , University of Nottingham	
<ul style="list-style-type: none"> <li>Designed physics-based locomotion for non-humanoid avatars and movements of extra body parts through inverse kinematics and procedural animation.</li> <li>Designed haptic feedback and visuomotor misalignment to simulate varied body weights and forces.</li> <li>Simulated vision features including color perception, echolocation, blurring vision.</li> <li>Conducted user study and semi-structured interviews, gathered qualitative data exploring body ownership.</li> </ul>	
<b>Fire Safety Training Through Virtual Reality Serious Gaming</b>	<b>2022.06 - 2022.10</b>
China Beacon Institute, University of Nottingham	
<ul style="list-style-type: none"> <li>Designed and developed fire extinguishing equipment training in non-immersive and immersive settings.</li> <li>Designed experiment workflow for analyzing the effectiveness of different simulation in terms of learning outcomes and user engagement and evaluating interaction preference of users.</li> </ul>	

## HONORS AND AWARDS

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Product Studio Finalist at Innovation Meets Impact	<b>2025</b>
University of Nottingham Ningbo China Outstanding Graduate	<b>2024</b>
Undergraduate Best Overall Performance Award	<b>2024</b>
Academic Excellence Scholarship (Provost's Scholarship)	<b>2021, 2022</b>
Zhejiang Provincial Scholarship	<b>2021</b>

## SKILLS

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**Languages:** C#, C++ (OpenGL, Vulkan), Python, JavaScript**Tools:** Unity, Unreal Engine, Figma, Adobe Photoshop, Blender